

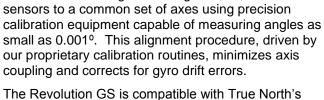
Revolutiontm GS - Gyro Stabilized Electronic Compass

If your compass application involves vibration, acceleration, uneven terrain, or rough seas, you will find the True North Revolution GS™ to be an uncompromising solution that will outperform rival units costing considerably more. The GS provides remarkably accurate heading, pitch, and roll in dynamic conditions. It all starts with a precision 3-axis solid-state magnetometer. Two angular rate gyros independently stabilize pitch and roll. They augment a dual-axis, electrolytic tilt sensor that provides precise tilt measurements in static environments. Two sets of independent filters, one set for pitch and one for roll, combine gyro and electrolytic sensor measurements to provide the best available tilt measurements.

The recommended applications for the GS are

manned and unmanned vehicles, robotics, weather buoys, antenna positioning, platform stabilization, marine navigation, excavation machinery, and irrigation equipment.

The exceptional performance of the GS is achieved by first calibrating all sensors over a wide temperature range.



Then True North aligns the magnetic, tilt, and rate

The Revolution GS is compatible with True North's Revolution Upgrade compass. The GS board fits in the same enclosure and has the same mounting hole pattern and connectors. Identical NMEA sentences are available, and the GS version includes additional binary data output for temperature and diagnostics.

The Revolution GS comes with an enhanced version of True North's demonstration software that is backward compatible with the Revolution Upgrade.

The magnetic calibration procedure required upon installation is identical, as are cabling and power requirements.

For more information, pricing, and availability, please e-mail: info@tntc.com.



Features

♦ Exceptional Dynamic Performance

- ⇒ Heading within 3° typical for rates < 150 °/sec
- ⇒ Pitch and roll within 3° for rates < 150 °/sec

♦ High Static Accuracy

- ⇒ Heading within 0.5° or better
- \Rightarrow Tilt within 0.2° or better

Wide Operating Range

- \Rightarrow ±42° Pitch and Roll
- \Rightarrow ±80° Dip angle range
- ⇒ Temperature -40° to 105°C
- \Rightarrow Local Hard Iron to ± 1.5 Gauss

♦ Precise Calibration

- ⇒ Gyros calibrated for offset and gain from -40 to 85C
- ⇒ Rate sensors calibrated and aligned to magnetometer and tilt sensor
- Cross-axis error nearly eliminated on gyros and magnetometer

♦ Single Supply Operation

- ⇒ 6 to 25V unregulated DC or
- ⇒ Reverse polarity protection

Fast Response

- ⇒ 28 readings per second
- ⇒ Wake from standby in 50 msec

Low Power

- ⇒ 30 mA operating
- ⇒ 10 mA sample
- ⇒ 2 mA standby

Wide Selection of ASCII or Binary Output data

- ⇒ Heading, pitch, and roll
- ⇒ Magnetometer X, Y, and Z
- ⇒ Temperature, input voltage, and dip angle
- ⇒ Output ASCII or binary
- ⇒ Horizontal X and Y magnetic field strength
- ⇒ Raw and conditioned gyro data

♦ Two independent serial channels

- ⇒ Full-duplex RS-232 for the external RJ12
- ⇒ Either RS-232 or full-duplex RS-485 for the internal connector

♦ In-System Configuration and Test

- ⇒ Laptop can be connected while unit operates in situ
- ⇒ Perform hard and soft iron calibration
- ⇒ Monitor outputs and change user-definable settings

True North Technologies LLC • 43 Broad St, Suite B308 • Hudson, MA 01749 USA Ph: 978-897-5400 • Email: info@tntc.com • Website: www.tntc.com

Specifications

Heading Performance

<u>Parameter</u>	<u>Value</u>	<u>Conditions</u>
Accuracy ¹	$\pm~0.5^{\circ}~\text{rms}$	Static, Tilt < 35° Dip < 60°
	\pm 3.0 $^{\circ}$ rms	Dynamic, rate < 150°/sec
Repeatability	± 0.3°	Static, no filter
Response time	36 msec	Minimum, no filter
Dip Angle Range	± 80°	
Tilt Range	± 42 °	
Update rate	28 per second	

¹ May require calibration after installation to eliminate effect of local magnetic field

Pitch and Roll Performance

Electrical

Supply Current 30 mA operating typical 10 mA sample typical 2 mA standby typical

Supply Voltage (V_{DD}) 6 − 25 Vdc unregulated

Environmental

Operating Temp -40 to 105°C Storage Temperature -50 to 150°C

Humidity 0 to 90% Non-condensing

Mechanical

Box Hammond Mfg1591MFL PCB Size 1.8"W x 3.0"L x 0.6"H

PCB Mounting 4 #4 screws, 1.4" x 2.2" spacing

Weight 4 oz. in box

Connectors 8 pin, single-row, 0.1" friction header

6 pin RJ12 modular jack

Interface

Signal type RS-232 and RS-485

Baud rate 2400, 4800, 9600, 19200, 38400, or 57600 bps

Character Format 8 data, no parity, 1 stop

Input Buffer Size 110 characters
Output Buffer Size 110 characters

Output Format NMEA 0183 and binary

Output Data Rate 1 to 1650 sentences per minute

Operating Modes Continuous or sample

Angle Units Degrees, mils, radians, 16-bit integer